

Failure Analysis in Photovoltaic Power Systems Using Artificial Neural Network

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Abstract:

As a result of the rapid expansion of photovoltaic systems, raising efficiency and managing maintenance became the PV systems' main factors. After that comes the cost and the time of repair immediately. This research provides an artificial neural network (ANN) to classify the system's type of failure. Three types of failure have been studied: line-to-line fault with a small voltage difference, a line-to-line fault with a large voltage difference, and ground fault. In addition to the fourth normal operation case, no failure is applied. The ANN employs five input data: power, voltage, current, temperature, and solar radiation. The output is a number from (0 to 3), each number denotes a specific type of failure: number '0' denotes the normal operation, number '1' denotes a line to line fault with a small voltage difference, number '2' denotes a ground fault, and number '3' denotes a line to line fault with a large voltage difference. Samples of collected data are used to train the ANN, with MATLAB Software Package, to model and simulate the system. Then, the proposed ANN is tested. Its ability to detect and classify the type of failure in the system is validated at a satisfactory success rate. The research's focus was on the discovery of a failure in the PV system, Not only the existence of a failure but also the discovery of the type of failure that occurred; this helps in speeding up the solution of the problem, speeding maintenance, and reducing the loss of power.

Keywords: Photovoltaic system, PV fault, the line-to-line fault, ground fault, PV faults simulation.

1. INTRODUCTION:

The emergence of the oil crises in the seventies has driven a major role in the development as the global PV industry developed at a rate with an average between 15% to 20% per year between 1991 to 2007 [1].

This tremendous development had great competition in the semiconductor and computer industry between 2000 and 2009. The growth of photovoltaic energy increased from 1428 to 22,893 megawatts at an average rate of 36.7% annually, making it the fastest-growing energy technology in the world [2]. The tremendous growth was mainly for preserving the environment, reducing pollution, and making it a clean environment [3-4].

The development of devices and different manufacturing methods had a tremendous role in raising solar cells' efficiency and reducing the size. With advanced manufacturing methods, the value per watt decreased from 16 US dollars to 8 US dollars per watt in 2007 [1].

Plans for solar energy produced by the International Energy Agency are estimated to provide photovoltaic energy, about 11% of global electricity generation by 2050. They will reduce 2.3 gigatonnes of carbon dioxide emissions annually. The result is that the photovoltaic industry plays an essential role in electricity. The result is in the

future [5-6]. Energy stations by 2030, including ten solar power stations. Some stations may produce 600 megawatts [7].

Countries have a useful role in the development of the photovoltaic energy industry. The Arab Republic of Egypt had a role in constructing solar energy stations and other renewable energy stations. Still, solar energy stations had the most considerable role and the highest concentration. Many stations were established that help produce electricity significantly from general productivity; Egypt plans to establish 25 new and renewable.

Table 1 Planned PV projects up to 2030 [7]

Project	Status	Size	Contract
Kom Ombo	Binding	200 MW	BOO scheme
West Nile	Binding	600 MW	Sky Power and EETC BOO
West Nile	Binding	200 MW	EETC BOO
West Nile	Binding	600 MW	BOO scheme
FIT	Operational	50 MW	EETC PPA
FIT	Under development	1415 MW	EETC PPA
Hurghada	Tendering	20 MW	NREA-JICA EPC scheme
Zaafarana	Under development	50 MW	NREA-AFD EPC scheme
Kom Ombo	Under development	26 MW	NREA-AFD EPC scheme
Kom Ombo	Under development	50 MW	NREA-AFD EPC scheme

As a result of the heavy use of photovoltaic panels, the failure of photovoltaic components increased. This failure is due to many reasons such as short circuit, open circuit, dust, and the derivation of photoelectric cells and shade. Failures affect the operating efficiency of the PV power generation

system. Improving the performance of the photovoltaic system requires the absence of any system failure. The failure can be classified into temporary failure and permanent fault in the photoelectric arrays. Both of which reduce the efficiency of the PV energy system. One of the

methods of failure detection is monitoring and analysis of the system. It collects primary data from the system at its normal operation state (no failure), such as voltage, current, power, and curve measurements, which give an overview analysis of the health system. The model and simulation must be able to produce the conclusion of similar behaviors to artificial intelligence systems. Artificial intelligence networks have many forms that differ in terms of construction and interconnection of networks with some. Modifications are made to the neural networks and trained to be consistent with the input data. The neural network is the result of the comparison between input and output. Therefore, there must be a comprehensive program to detect the failure and detect the type of failure because some programs only discover the failure. Still, this program is designed to discover the type of failure to reduce the repair time. The employed system here is an Artificial Neural Network (ANN) based system.

Among the most common concerns about solar energy are faults, inaccuracies in solar energy matrices, and failure during conduction. As a result of faults, several risks occur, such as electric shock and fire exposure, efficiency decrease, and even power outage. In this work, three types of failure have been studied: line to line fault with a small voltage difference, a line to line fault with a large voltage difference, and ground fault, In addition to the fourth normal fault, where no failure is applied. The research sheds light on discovering the photoelectric system's failure and determining the type of failure that occurs through the neural network. Matlab/Simulink is used to model the photoelectric system and apply the neural network to discover the type of failure. It had high-efficiency results, and determining the type of failure helps in the speed and eases of solving the system Maintenance and reduced power loss.

2. PV SYSTEM DESCRIPTION

The solar PV system includes various components that must be calculated and determined according to the consumption of electrical appliances, storage, solar cells, and the solar system's location and available area to be covered by PV panels. Fig. 1 shows a block diagram of the typical stand-alone PV power system. It can be described as follows:

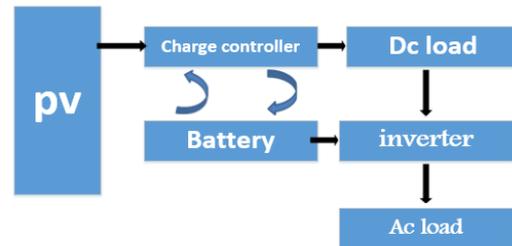


Fig. 1: Block diagram of the typical stand-alone PV power system.

2.1 PV modules:

Solar cells are made of semiconductors, and their function is to convert the light produced by the sun into DC electricity. Fig. 2 shows a single-diode model of solar cells [8].

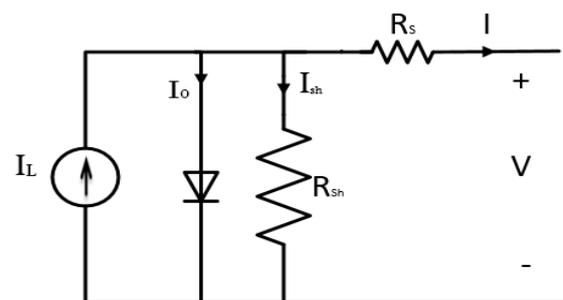


Fig. 2 Single-diode model of solar cell

Such PV model can be represented by the following equation [8]:

$$I_L - I_S \left[\exp \left(\frac{(1 + R_S)}{AKT} q \right) - 1 \right] - \left(\frac{V + IR_S}{R_P} \right) \quad (1)$$

Where, I = solar cell current (A), V = solar cell voltage (V), I_L = light-generated current (A), I_S = saturation current of the diode (A), R_S = solar cell series resistance (ohms), R_P = solar cell shunt

resistance (ohms), q (electron charge) = 1.6×10^{-19} C, K = Boltzmann's constant = 1.38×10^{-23} J/K, A = diode ideality factor ($1 \leq A \leq 2$), T = ambient temperature (K). Depending on solar irradiance and ambient temperature, the light generated current I_L is described as [8]:

$$I_L = \left(\frac{G}{G_0}\right) [I_{L_0} + C_T(T - T_0)] \quad (2)$$

Where, G = solar irradiance (W/m^2), G_0 = reference solar irradiance (W/m^2) = reference light generated current (A), T_0 = reference temperature (K), C_T = temperature coefficient of the light generated current (A/K). Furthermore, the saturation current I_S of the diode is varying with the temperature, as follows [8]:

$$I_S = I_{S_0} \left(\frac{T}{T_0}\right)^3 \exp \left[\frac{qE_G}{AK} \left(\frac{1}{T_0} - \frac{1}{T}\right) \right] \quad (3)$$

Where E_g is the bandgap energy of the material (eV).

3. SIMULATION OF PV SYSTEM

The photovoltaic array usually consists of several solar cells identical in characteristics and specifications to fulfill load demand. The voltage and current are determined at the maximum and highest PowerPoint of operation. Geography, temperature, and solar radiation level vary, and the level of solar radiation is the main input for the solar cells. Furthermore, some other factors may affect the photovoltaic system operation, such as failures that significantly impact reducing the energy output of the PV system.

After attempts to design a photovoltaic power system under normal working conditions and operating conditions where a particular failure occurs, a Matlab program was designed to carry out simulations, extract results, and apply the studied cases to the photovoltaic array.

The solar cells were carefully studied, and during the design, the temperature and the level of solar radiation were taken as inputs, whether current, volts, and power as outputs.

Failure operating cases are applied to the PV array, and both current and voltage are identified. The same type of cells and the exact specifications and features are used in the PV array.

Table 2 illustrates the used PV module data, including maximum power, open-circuit voltage, the voltage at the maximum power point, number of cells in a module, short circuit current, current at the maximum power point, and temperature coefficient for voltage and current [8].

Table 2: Module data of PV array

Maximum Power (W)=83.2824	Cells per module (No. cell)=60/3
Open circuit voltage V_{oc} (V)=12.64	Short-circuit current I_{sc} (A)=8.82
The voltage at maximum power point V_{mp} (V)=10.32	Current at maximum power point I_{mp} (A)=8.07
Temperature coefficient of V_{oc} (%/deg.C)=0.33969	Temperature coefficient of I_{sc} (%/deg C)=0.063701

3.1 Simulation of the normal condition

PV system model is built using MATLAB Simulink, and the model is tested for various operating conditions. Results are drowning in

curves, which are mainly based on the fault under the PV system study. As shown in Fig. 3, sixteen PV panels are connected in a series/parallel combination, where no failure is applied. The test is carried out in more than one point/line in the system

3.2 Simulation of Line to Line Fault (small voltage difference)

Inline to small line voltage is simulated by creating a short circuit between the strings of PV modules. As shown in Fig.4, a short circuit is applied between solar cells no. (1-2) and solar cells no. (6-7). A line-to-line voltage is considered a short circuit that causes the PV system modules' power to decrease dramatically [9].

3.3 Simulation of Line to Line Fault (large voltage difference)

The inline line-to-line fault with a large voltage difference is simulated by creating a short circuit between PV modules' strings. As shown in Fig. 5, the fault is applied by connecting a short circuit between solar cells. (1-2) and solar cells no. (7-8) such line-to-line voltage causes the power of the PV system modules to decrease dramatically.

3.4 Simulation of Ground Fault

As shown in Fig. 6, a ground fault is applied. A ground fault is the most prevalent type between faults of PV systems. With this fault, current flow occurs through the ground conductor before reaching the inverter, and it causes many problems to the system that may lead to fires [10-11].

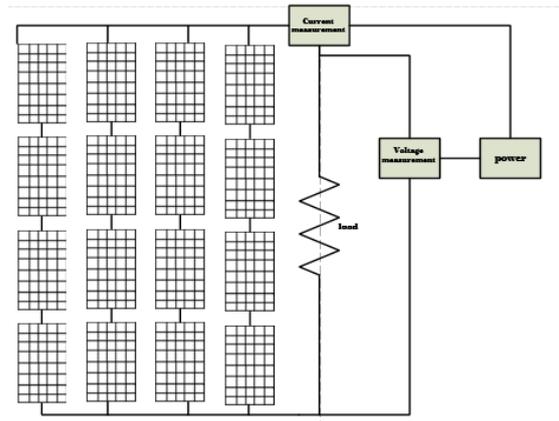


Fig.3 PV system at the normal operating condition.

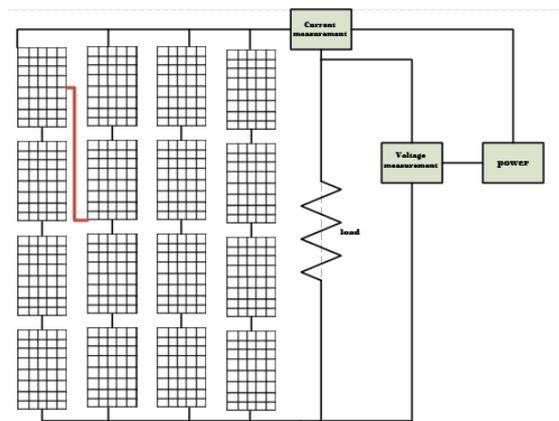


Fig.4 PV system with a line-to-line fault (small voltage difference).

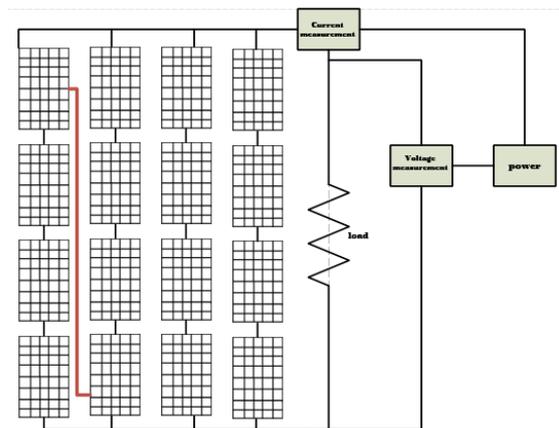


Fig.5 PV system with a line-to-line fault (large voltage difference).

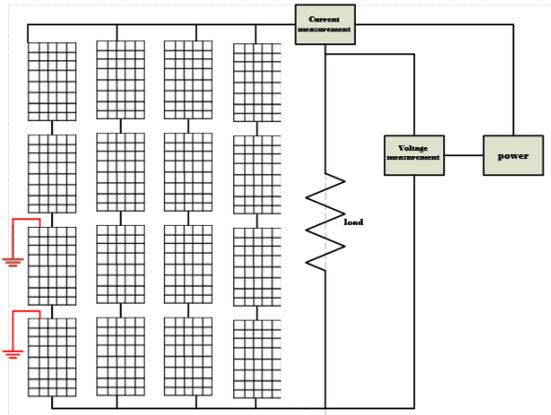


Fig.6 PV system with ground fault

4. DATA COLLECTION

After simulating the PV arrays and testing various faults, the next step is data collection for every type of fault and comparing the three outputs (current-voltage-power). The data has been collected as illustrated in the following tables (Table 3 to Table 6). Tables include measured quantities at the maximum power point (voltage, current, and power) in various cases (normal operation, the line to line fault with small voltage, the line to line fault with large voltage, and ground fault) and at different solar radiation/temperature. Furthermore, PV curves help to detect the failure occur in the PV energy systems. [12].

5. PROPOSED ANN BASED FAULT DETECTION SYSTEM

5.1 Design of the Artificial Neural Network

Artificial intelligence networks (ANNs) have many forms that may differ in terms of construction and interconnection of neurons.

ANN modeling and simulation should be able to create similar behaviors in industrial systems. ANN works by processing the information and presenting the information in the form of mutations. The ANN consists of a group of neurons (as shown in Fig. 7) connected according to a specific shape and the formation of an organized architectural way [13],[14].

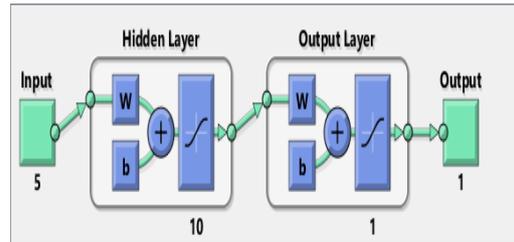


Fig. 7 Structure of a typical artificial neural.

The recorded data are split into two subsets: a training data set (70% of patterns, a sample is addressed in Table 7), which is used to evaluate the gradient and to readjust the network weights and bias, and a test set (the other 30% patterns). The latter set is used to validate the Multi-Layer Perceptron model by comparing the actual data with the estimated output.

5.2 Fault Classification

A fault detection model is developed using an ANN. The ANN model consists of five inputs: temperature, irradiance, maximum voltage, maximum current, and maximum power. It has one output: fault number, as shown in Fig. 8. The single output is a number, and this number denotes the fault type is addressed in Table 8. The table illustrates the output corresponding to the type of fault. Hence, it is easier to identify the type of failure more easily and quickly, making the modeling process easier [15], [16].

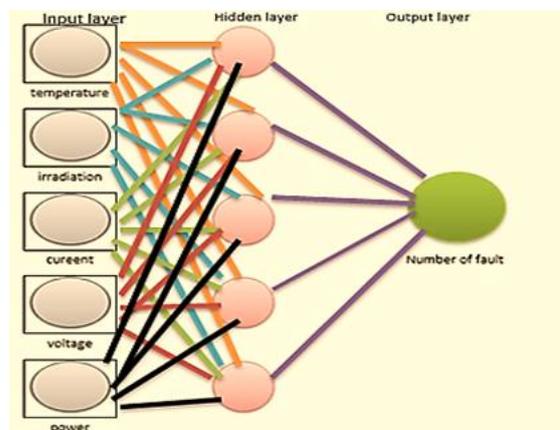


Fig.8 Proposed ANN-based fault detector.

Table 8. The output corresponding to the type of fault

Type of fault	number
Normal operation	0
Line to line with a small voltage difference	1
Ground fault	2
Line to line with a large voltage difference	3

Table 3. Data collected at solar irradiance of 1000 W/m²

Temperature	I_m (normal operation)	I_m (L-L with small voltage difference)	I_m (L-L with large voltage difference)	I_m (ground fault)	V_m (normal operation)	V_m (L-L with small voltage difference)	V_m (L-L with large voltage difference)	V_m (ground fault)	P_m (normal operation)	P_m (L-L with small voltage difference)	P_m (L-L with large voltage difference)	P_m (ground fault)
20	32.2277	32.0439	32.1359	32.0401	42.1670	34.3555	22.9290	34.3302	1.3589	1.1009	736.8438	1.0999
25	32.2866	32.0871	32.1518	32.0699	41.2696	33.7362	22.5371	33.7235	1.3325	1.0825	724.6084	1.0815
30	32.3239	32.1154	32.1837	32.0962	40.3974	33.1294	22.1326	33.1168	1.3058	1.0640	712.3094	1.0629
35	32.3691	32.1406	32.2139	32.1314	39.5126	32.5227	21.7282	32.4974	1.2790	1.0453	699.9479	1.0442
40	32.4021	32.1623	32.2233	32.1501	38.6405	31.9160	21.3363	31.8907	1.2520	1.0265	687.5262	1.0253
45	32.4536	32.1932	32.2498	32.1903	37.7430	31.2966	20.9318	31.2587	1.2249	1.0075	675.0476	1.0062

Table 4. Data collected at an irradiance of 800 W/m²

Temperature	I_m (normal operation)	I_m (L-L with small voltage difference)	I_m (L-L with large voltage difference)	I_m (ground fault)	V_m (normal operation)	V_m (L-L with small voltage difference)	V_m (L-L with large voltage difference)	V_m (ground fault)	P_m (normal operation)	P_m (L-L with small voltage difference)	P_m (L-L with large voltage difference)	P_m (ground fault)
20	19.3768	19.3711	19.4302	19.3559	42.3440	34.1406	22.7773	34.1406	820.4920	661.3434	442.5677	660.8217
25	19.4178	19.3971	19.4536	19.3958	41.4213	33.5086	22.3602	33.4834	804.3114	649.9718	434.9850	649.4376
30	19.4397	19.4216	19.4757	19.4046	40.5365	32.8766	21.9430	32.8766	788.0186	638.5158	427.3568	637.9587
35	19.4726	19.4443	19.4967	19.4337	39.6264	32.2446	21.5259	32.2320	771.6290	626.9750	419.6851	626.3866
40	19.4982	19.4652	19.5166	19.4610	38.7290	31.6126	21.1088	31.5874	755.1435	615.3468	411.9712	614.7217
45	19.5224	19.4842	19.5352	19.4784	37.8315	30.9806	20.6917	30.9554	738.5627	603.6345	404.2163	602.9599

Table 5. Data collected at an irradiance of 600 W/m²

Temperature	I_m (normal operation)	I_m (L-L with small voltage difference)	I_m (L-L with large voltage difference)	I_m (ground fault)	V_m (normal operation)	V_m (L-L with small voltage difference)	V_m (L-L with large voltage difference)	V_m (ground fault)	P_m (normal operation)	P_m (L-L with small voltage difference)	P_m (L-L with large voltage difference)	P_m (ground fault)
20	25.8167	25.7318	25.8126	881.6886	42.3061	34.2923	22.8784	34.2797	1.0922	882.4042	590.5510	881.6886
25	25.8526	25.7718	25.8350	25.7593	41.4213	33.6603	22.4739	33.6477	1.0708	867.4885	580.6136	866.7412
30	25.8869	25.8002	25.8705	25.7863	40.5365	33.0410	22.0568	33.0283	1.0494	852.4624	570.6204	851.6785
35	25.9274	25.8363	25.8897	25.8207	39.6390	32.4090	21.6523	32.3963	1.0277	837.3262	560.5731	836.4942
40	25.9667	25.8598	25.9073	25.8420	38.7416	31.7896	21.2478	31.7770	1.0060	822.0711	550.4733	821.1808
45	25.9874	25.8700	25.9388	25.8602	37.8694	31.1829	20.8307	31.1576	0.9841	806.7018	540.3232	805.7406

Table 6. Data collected at irradiance of 400 W/m²

Temperature	I_m (normal operation)	I_m (L-L with small voltage difference)	I_m (L-L with large voltage difference)	I_m (ground fault)	V_m (normal operation)	V_m (L-L with small voltage difference)	V_m (L-L with large voltage difference)	V_m (ground fault)	P_m (normal operation)	P_m (L-L with small voltage difference)	P_m (L-L with large voltage difference)	P_m (ground fault)
20	12.9301	12.9510	12.9871	12.9411	42.1418	33.8499	22.5877	33.8499	544.8955	438.3903	293.3488	438.0545
25	12.9496	12.9692	13.0057	12.9637	41.2317	33.2053	22.1579	33.1926	533.9345	430.6457	288.1801	430.3010
30	12.9724	12.9863	13.0236	12.9804	40.3090	32.5606	21.7282	32.5480	522.9040	422.8427	282.9799	422.4855
35	12.9904	13.0023	13.0408	13.0009	39.3989	31.9160	21.2984	31.8907	511.8056	414.9818	277.7490	414.6071
40	13.0074	13.0223	13.0573	13.0149	38.4888	31.2587	20.8686	31.2461	500.6410	407.0604	272.4882	406.6648
45	13.0236	13.0412	13.0730	13.0328	37.5787	30.6014	20.4389	30.5888	489.4117	399.0789	267.1982	398.6574

Table 7. Sample of the training data set for ANN

Temperature	20	20	25	25	30	30	45	45
Irradiation	800	1000	800	1000	800	1000	600	400
V_{max}	42.3061	42.167	33.6603	33.7362	33.0283	33.1168	20.6917	20.4389
I_{max}	25.8167	32.2277	25.7718	32.0871	25.7863	32.0962	19.5352	13.073
P_{max}	1.09E+03	1.36E+03	867.4885	1.08E+03	851.6785	1.06E+03	404.2163	267.1982
Fault No.	0	0	1	1	2	2	3	3

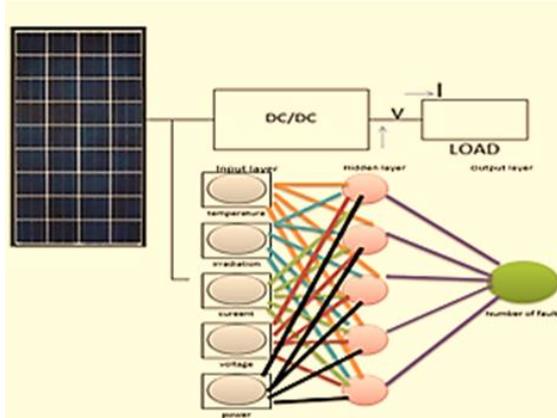


Fig.9 The block of the proposed ANN-based fault detection system.

5.3 Fault Detection System

The proposed ANN-based fault detection system has five inputs: temperature, solar radiation, voltage, current, and power at the maximum power point, as shown in Fig. 9. The ANN has been trained with the training dataset and tested from the remaining collected and simulated data. The result can be validated for the correct value of output denoting the fault status after the input dataset is applied to the proposed ANN-based fault detection system.

6. APPLICATION AND OPERATION

6.1 Training of the ANN

The ANN is trained using the training data set so that the weights are determined, and the ANN is formulated, as shown in Fig.10.

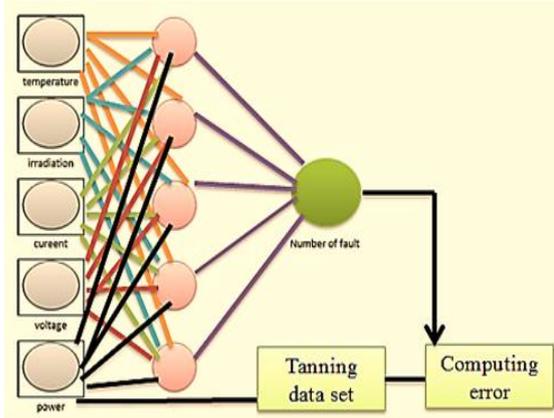


Fig.10 Adjustment of the ANN

The proposed ANN is trained at different solar radiations (1000, 800, 600, and 400) and different temperatures (20, 25, 30, 35, 40, and 45). The training was done on every radiation with all temperatures and even on all operating cases (normal and faulty conditions).

6.2 Testing of the ANN

Table 9 addresses a sample of the test data set for ANN. The test data set is applied to the fault detection model. Fig. 11 shows the evolution of the performance error of the developed ANN-model. It is observed that the mean square error during the training process is about 10⁻³ (the best performance validation of the performance is at 0.22408 at epoch 9). This outcome points out that the weights and bias of the network are well adjusted, and the model could reproduce the output data with reasonable accuracy. The regression

value is close to 1, yet there is a perfect correlation between targets and outputs [17]-[21].

Table 9. Sample of the test data set for ANN

Temperature	19	29	33	24	19	32	23	21
Irradiation	900	950	350	390	970	750	790	810
V_{max}	42.4198	40.625	39.639	33.319	34.4693	32.7502	22.6256	22.8026
I_{max}	29.0197	30.7023	11.3629	12.6406	31.0958	24.2062	25.5156	26.1331
P_{max}	1.23E+03	1.25E+03	450.413	421.171	1.07E+03	792.7592	577.3035	595.9022
Fault No.	0	0	0	1	1	2	3	3
Output of ANN	0.0078	0.0091	0.0106	1.434	1.1051	1.5205	2.9283	2.931

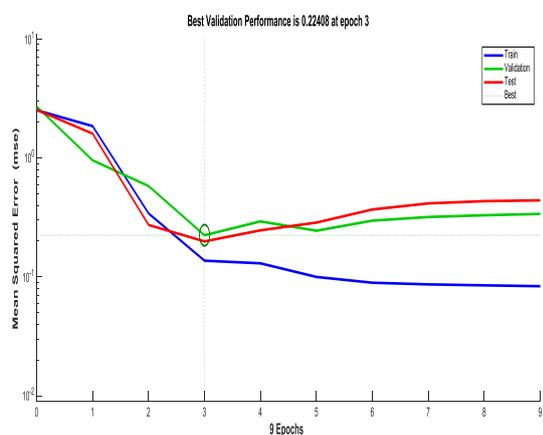


Fig.11 Performance test of proposed ANN fault detector

6.3 Operation of the ANN

When input data is applied to the proposed ANN-based fault detection system, the ANN's output is displayed as the number of faults, as shown in Fig. 12. Accordingly, the output is classified, as illustrated in Table 10, the type of the fault is determined. Therefore, it became easy to determine the type of occurred fault [22]-[27]. The inputs (x_1) are in the order {temperature, solar irradiance, V_{max} , I_{max} , P_{max} }, and the output (y_1) is a number from (0 to 3), each number specifies a specific type

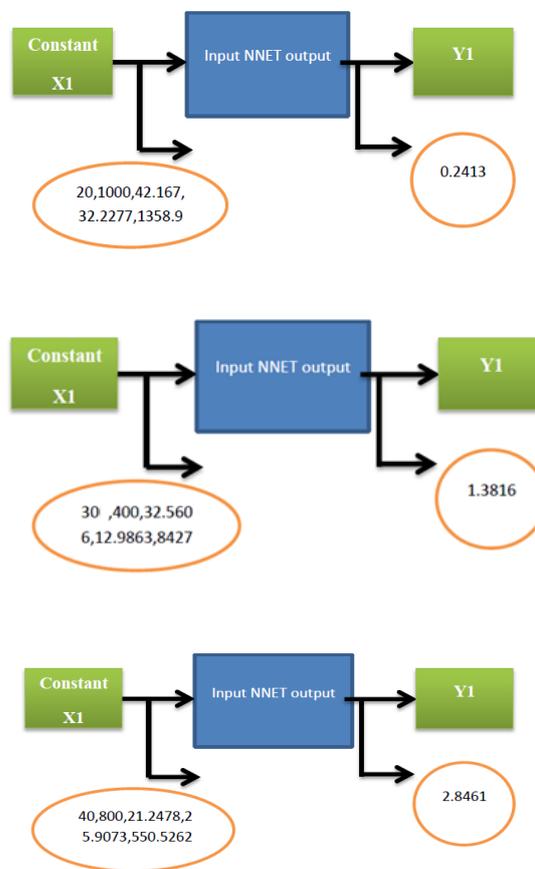


Fig. 12 Three examples show the operation of the proposed ANN-based fault detection system.

Of failure, number '0' denotes the normal operation, number '1' denotes a line to line fault with a small voltage difference, number '2' refers to a ground fault, and number '3' presents a line to line fault with a large voltage difference.

Table 10.Operation of the proposed ANN

Out of test data	Type of fault
0-0.6	0
0.7-1.6	1
1.7-2.5	2
2.6-3	3

7. CONCLUSIONS AND FUTURE WORK

A proposed ANN-based detection system has been designed and investigated to detect and classify faults in a PV power system. Results obtained through simulation showed the proposed system's efficiency to detect and classify the type of fault. This is achieved by collecting data like the voltage, current, and power at the maximum power point, in addition to the solar radiation and temperature. The proposed detection system proved its capability to operate at a different temperature, solar radiation, and applied faults with a quick response. Accordingly, when installing a PV power system, the proposed detector's presence will help in the protection process and reduce the PV outage periods and hence increase the PV power systems reliability. The future study includes monitoring the whole PV system, identifying the faulty section, and integrating it with the protective device to clear the fault.

Appendix:

A) ABBREVIATIONS

BOO	build-own-operate
EETC	Egyptian Electricity Transmission Company
AFD	Agence Française de Développement
JICA	Japan International Cooperation Agency
NREA	New and Renewable Energy Authority

PPA	power purchase agreement
EPC	engineering, procurement, and construction

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الملخص :

بعد تفاقم أزمة الطاقة الأحفورية وصعوبة الحصول عليها ، كان للطاقة المتجددة دور أساسي في توفير الطاقة كمصدر بديل نظيف واستراتيجي. ومن أهم مصادر الطاقة المتجددة الخلايا الشمسية. ونتيجة للتوسع السريع في الأنظمة الكهروضوئية ، أصبح رفع الكفاءة وإدارة الصيانة من العوامل الهامة والرئيسية في الأنظمة الكهروضوئية. ثم تأتبعها التكلفة ووقت الإصلاح. ويقدم هذا البحث شبكة عصبية اصطناعية (ANN) لتصنيف نوع فشل النظام. وقد تمت دراسة ثلاثة أنواع من الخطأ: خطأ من خط إلى خط بفرق جهد صغير ، وخطأ من خط إلى خط بفرق جهد كبير ، وخطأ أرضي. بالإضافة إلى حالة التشغيل العادية (حالة الدراسة الرابعة) ، ويعد استخدام خمسة بيانات إدخال لمنظومة ANN مشاركةً أصيلةً للبحث: القدره والجهد والتيار ودرجة الحرارة والإشعاع الشمسي. وتنتج ANN رقماً قيمته ما بين (0 إلى 3) ، وكل رقم يحدد نوعاً معيناً من الخطأ ، والرقم "0" يشير إلى حالة التشغيل العادية ، والرقم "1" يشير إلى حالة خطأ خط إلى خط بجهد صغير ، أما رقم "2" فيشير إلى حالة خطأ أرضي ، كما يشير رقم "3" إلى حالة خطأ خط الي خطأ بجهد كبير. وقد تم استخدام عينات من البيانات المجمعة لتدريب ANN ، مع MATLAB Software Package ، لنمذجة ومحاكاة النظام. ثم تم اختبار ANN المقترح. وتم التحقق من قدرة ANN المقترحة على اكتشاف وتصنيف نوع الفشل الذي قد يحدث في النظام بمعدل نجاح قادر على التصنيف وكان التركيز في البحث ليس مقتصرًا فقط على اكتشاف وجود خطأ بل تحديد نوع الخطأ وذلك يسهل في عملية صيانته ويقال من فقد ف الطاقة .